

## Question “Orange”

1.1)

First of all, we use the Gauss’s law for a single plate to obtain the electric field,

$$E = \frac{\sigma}{\epsilon_0}. \quad (0.2)$$

The density of surface charge for a plate with charge,  $Q$  and area,  $A$  is

$$\sigma = \frac{Q}{A}. \quad (0.2)$$

Note that the electric field is resulted by two equivalent parallel plates. Hence the contribution of each plate to the electric field is  $\frac{1}{2}E$ . Force is defined by the electric field times the charge, then we have

$$\text{Force} = \frac{1}{2}EQ = \frac{Q^2}{2\epsilon_0 A} \quad (0.2) + (0.2) \quad (\text{The } \frac{1}{2} \text{ coefficient} + \text{the final result})$$

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1.2)

The Hook’s law for a spring is

$$F_m = -kx. \quad (0.2)$$

In 1.2 we derived the electric force between two plates is

$$F_e = \frac{Q^2}{2\epsilon_0 A}.$$

The system is stable. The equilibrium condition yields

$$F_m = F_e, \quad (0.2)$$

$$\Rightarrow x = \frac{Q^2}{2\epsilon_0 A k} \quad (0.2)$$

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1.3)

The electric field is constant thus the potential difference,  $V$  is given by

$$V = E(d - x) \quad (0.2)$$

(Other reasonable approaches are acceptable. For example one may use the definition of capacity to obtain  $V$ .)

By substituting the electric field obtained from previous section to the above equation, we

$$\text{get, } V = \frac{Qd}{\epsilon_0 A} \left( 1 - \frac{Q^2}{2\epsilon_0 A k d} \right) \quad (0.2)$$

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1.4)

$C$  is defined by the ratio of charge to potential difference, then

$$C = \frac{Q}{V}. \quad (0.1)$$

Using the answer to 1.3, we get  $\frac{C}{C_0} = \left(1 - \frac{Q^2}{2\epsilon_0 A k d}\right)^{-1}$  (0.2)

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1.5)

Note that we have both the mechanical energy due to the spring

$$U_m = \frac{1}{2} k x^2, \quad (0.2)$$

and the electrical energy stored in the capacitor.

$$U_E = \frac{Q^2}{2C}. \quad (0.2)$$

Therefore the total energy stored in the system is

$$U = \frac{Q^2 d}{2\epsilon_0 A} \left(1 - \frac{Q^2}{4\epsilon_0 A k d}\right) \quad (0.2)$$

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2.1)

For the given value of  $x$ , the amount of charge on each capacitor is

$$Q_1 = V C_1 = \frac{\epsilon_0 A V}{d - x}, \quad (0.2)$$

$$Q_2 = V C_2 = \frac{\epsilon_0 A V}{d + x}. \quad (0.2)$$

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2.2)

Note that we have two capacitors. By using the answer to 1.1 for each capacitor, we get

$$F_1 = \frac{Q_1^2}{2\epsilon_0 A},$$

$$F_2 = \frac{Q_2^2}{2\epsilon_0 A}.$$

As these two forces are in the opposite directions, the net electric force is

$$F_E = F_1 - F_2, \quad (0.2) \quad \Rightarrow \quad F_E = \frac{\epsilon_0 A V^2}{2} \left( \frac{1}{(d-x)^2} - \frac{1}{(d+x)^2} \right) \quad (0.2)$$

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2.3)

Ignoring terms of order  $x^2$  in the answer to 2.2., we get

$$F_E = \frac{2\epsilon_0 A V^2}{d^3} x \quad (0.2)$$

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2.4)

There are two springs placed in series with the same spring constant,  $k$ , then the mechanical force is

$$F_m = -2kx. \quad (\text{The coefficient (2) has (0.2)})$$

Combining this result with the answer to 2.4 and noticing that these two forces are in the opposite directions, we get

$$F = F_m + F_E, \quad \Rightarrow \quad F = -2 \left( k - \frac{\epsilon_0 A V^2}{d^3} \right) x, \quad (\text{Opposite signs of the two forces have (0.3)})$$

$$\Rightarrow k_{\text{eff}} = 2 \left( k - \frac{\epsilon_0 A V^2}{d^3} \right) \quad (0.2)$$


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2.5)

By using the Newton's second law,

$$F = ma \quad (0.2)$$

and the answer to 2.4, we get

$$a = -\frac{2}{m} \left( k - \frac{\epsilon_0 A V^2}{d^3} \right) x \quad (0.2)$$


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3.1)

Starting with Kirchhoff's laws, for two electrical circuits, we have

$$\left\{ \begin{array}{l} \frac{Q_s}{C_s} + V - \frac{Q_2}{C_2} = 0 \\ -\frac{Q_s}{C_s} + V - \frac{Q_1}{C_1} = 0 \\ Q_2 - Q_1 + Q_s = 0 \end{array} \right. \quad (\text{Each has (0.3), Note: the signs may depend on the specific choice made})$$

Noting that  $V_s = \frac{Q_s}{C_s}$  one obtains

$$\Rightarrow V_s = V \frac{\frac{2\epsilon_0 A x}{d^2 - x^2}}{C_s + \frac{2\epsilon_0 A d}{d^2 - x^2}} \quad ((0.4) + (0.2): (0.4) \text{ for solving the above equations and (0.2)})$$

for final result)

Note: Students may simplify the above relation using the approximation  $d^2 \gg x^2$ . It does not matter in this section.

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3.2)

Ignoring terms of order  $x^2$  in the answer to 3.1., we get

$$V_S = V \frac{2\epsilon_0 A x}{d^2 C_S + 2\epsilon_0 A d} . \quad (0.2)$$

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4.1)

The ratio of the electrical force to the mechanical (spring) force is

$$\frac{F_E}{F_m} = \frac{\epsilon_0 A V^2}{k d^3} ,$$

Putting the numerical values:

$$\frac{F_E}{F_m} = 7.6 \times 10^{-9} . \quad ((0.2) + (0.2) + (0.2): (0.2) \text{ for order of magnitude, } (0.2) \text{ for}$$

two significant digits and (0.2) for correct answer (7.6 or 7.5)).

As it is clear from this result, we can ignore the electrical forces compared to the electric force.

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4.2)

As seen in the previous section, one may assume that the only force acting on the moving plate is due to springs:

$$F = 2k x . \quad (\text{The concept of equilibrium } (0.2))$$

Hence in mechanical equilibrium, the displacement of the moving plate is

$$x = \frac{ma}{2k} .$$

The maximum displacement is twice this amount, like the mass spring system in a gravitational force field, when the mass is let to fall.

$$x_{\max} = 2x \quad (0.2)$$

$$x_{\max} = \frac{ma}{k} \quad (0.2)$$

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4.3)

At the acceleration

$$a = g , \quad (0.2)$$

The maximum displacement is

$$x_{\max} = \frac{mg}{k} .$$

Moreover, from the result obtained in 3.2, we have

$$V_s = V \frac{2\epsilon_0 A x_{\max}}{d^2 C_s + 2\epsilon_0 A d}$$

This should be the same value given in the problem, 0.15 V .

$$\Rightarrow C_s = \frac{2\epsilon_0 A}{d} \left( \frac{V x_{\max}}{V_s d} - 1 \right) \quad (0.2)$$

$$\Rightarrow C_s = 8.0 \times 10^{-11} \text{ F} \quad (0.2)$$


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4.4)

Let  $\ell$  be the distance between the driver's head and the steering wheel. It can be estimated to be about

$$\ell = 0.4 \text{ m} - 1 \text{ m} . \quad (0.2)$$

Just at the time the acceleration begins, the relative velocity of the driver's head with respect to the automobile is zero.

$$\Delta v(t=0) = 0, \quad (0.2)$$

then

$$\ell = \frac{1}{2} g t_1^2 \quad \Rightarrow \quad t_1 = \sqrt{\frac{2\ell}{g}} \quad (0.2)$$

$$t_1 = 0.3 - 0.5 \text{ s} \quad (0.2)$$


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4.5)

The time  $t_2$  is half of period of the harmonic oscillator, hence

$$t_2 = \frac{T}{2}, \quad (0.3)$$

The period of harmonic oscillator is simply given by

$$T = 2\pi \sqrt{\frac{m}{2k}}, \quad (0.2)$$

therefore,

$$t_2 = 0.013 \text{ s} . \quad (0.2)$$

As  $t_1 > t_2$ , the airbag activates in time. (0.2)